

# Econometric Methods for Panel Data

Based on the books by BALTAGI: *Econometric Analysis of Panel Data* and by HSIAO: *Analysis of Panel Data*

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April 25, 2018

# Outline

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## The hypotheses of poolability tests

These tests help select the panel model to be estimated, within the framework of fixed-effects models. For example:

- ▶ Are there individual effects or is it preferable to ignore them and to estimate by pooled OLS?
- ▶ Are there time effects on top of the individual effects?
- ▶ Are the coefficients  $\beta$  really constant across individuals?

These tests follow a simple principle: restricted and unrestricted models are compared via LR or Wald statistics. In most cases, null distributions are  $F$  or  $\chi^2$ , with degrees of freedom matching the number of restrictions.

## Testing for individual effects

Here, the null model (restricted) is

$$y_{it} = \alpha + \beta' X_{it} + \nu_{it},$$

with *iid* errors, and the alternative (unrestricted) model is

$$y_{it} = \alpha + \beta' X_{it} + \mu_i + \nu_{it},$$

assuming  $\sum_{i=1}^N \mu_i = 0$ . The null hypothesis may be written as:

$$H_0 : \mu_i = 0, i = 1, \dots, N.$$

## Testing for individual effects: the statistic

The traditional restriction-test statistic is

$$F_{1-way} = \frac{(ESS_R - ESS_U) / (N - 1)}{ESS_U / ((T - 1)N - K)},$$

as there are  $N - 1$  restrictions from the maintained hypothesis to the null. There are  $(T - 1)N - K$  degrees of freedom in the unrestricted model. Under  $H_0$ , this statistic will be distributed as  $F_{N-1, N(T-1)-K}$ , assuming Gaussian errors.

## Other analogous tests

For the null of the pooled model and the alternative of the two-way model, the distribution of the  $F$ -statistic will be distributed as  $F_{(N+T-2, NT-N-T+1-K)}$  under the null, assuming Gaussian errors.

For the null of the one-way individual-effects model and the alternative of the two-way model, the  $F$ -statistic will be distributed as  $F_{(T-1, NT-N-T+1-K)}$  under the null, assuming Gaussian errors.

For large  $NT$ ,  $\chi^2$  versions may be used instead, which are independent of Gaussian error assumptions.

## Testing homogeneity of individual slopes

In one specification, the unrestricted model is

$$y_{it} = \alpha + \beta_i' X_{it} + \mu_i + \nu_{it},$$

and the null can be expressed as

$$H_0 : \beta_1 = \dots = \beta_N = \beta, \mu_1 = \dots = \mu_N = 0,$$

with  $(K + 1)(N - 1)$  restrictions. The unrestricted model has only  $N(T - K - 1)$  degrees of freedom. If this test rejects, either the one-way model should be considered or individuals must be modelled separately. It may make more sense just to test the slopes, with  $K(N - 1)$  restrictions.

# Constellations in panel models and degrees of freedom

effects	name	coefficients $\beta$	
		$\beta$	$\beta_i$
$\alpha$	OLS	$NT - K - 1$	$N(T - K) - 1$
$\alpha_i$	one-way	$N(T - 1) - K$	$N(T - K - 1)$
$\alpha_{it}$	two-way	$N(T - 1) - T + 1 - K$	$N(T - K - 1) - T + 1$



## The test by ROY and ZELLNER

Some researchers (among them, BALTAGI) criticize that the usual  $F$ -test checks poolability in an otherwise perfect Gauss-Markov regression with  $E\nu\nu' = \sigma_\nu^2\mathbf{I}$ . To cope with this problem, one may also test for  $\beta_i = \beta$  and/or  $\beta_t = \beta$  in a (one-way or two-way) RE model.

This test is called the Roy-Zellner test. Essentially, it tests for 'fixed-type' poolability of slope coefficients in a random-effects model.

## Likelihood-ratio tests for variance parameters

Assume  $L_u$  is the likelihood of an unrestricted model,  $L_r$  is the likelihood of a restricted model. A lemma says that the *likelihood-ratio* (LR) statistic

$$LR = 2 (\log L_u - \log L_r),$$

will be, under the null of the restricted model, asymptotically distributed  $\chi^2$  with degrees of freedom matching the number of restrictions.

The lemma requires several *regularity conditions*. In testing a variance parameter for zero, these conditions are violated and the property is not guaranteed to hold.

## LR test for random effects in two-way panels

The unrestricted RE model

$$y_{it} = \alpha + \beta' X_{it} + u_{it},$$

$$u_{it} = \mu_i + \lambda_t + \nu_{it},$$

with the restricted null  $H_0 : \sigma_\mu^2 = \sigma_\lambda^2 = 0$  violates the regularity conditions. The LR test statistic has the non-standard distribution

$$\frac{1}{4}\chi^2(0) + \frac{1}{2}\chi^2(1) + \frac{1}{4}\chi^2(2),$$

where  $\chi^2(0)$  denotes point mass at zero.

## LR test for random effects in one-way panels

The unrestricted RE model

$$y_{it} = \alpha + \beta' X_{it} + u_{it},$$

$$u_{it} = \mu_i + \nu_{it},$$

with the restricted null  $H_0 : \sigma_{\mu}^2 = 0$  again violates the regularity conditions. The LR test statistic has the non-standard distribution

$$\frac{1}{2}\chi^2(0) + \frac{1}{2}\chi^2(1).$$

An analogous test can be used for random time effects. These tests are due to GOURIEROUX, HOLLY & MONFORT.

## LM tests for random effects

Lagrange-multiplier (LM) tests have standard  $\chi^2$  asymptotics. They have usually less power. One may test for two-way random effects using pooled-OLS residuals  $\tilde{u}$  by *LM*:

$$LM = LM_1 + LM_2,$$

$$LM_1 = \frac{NT}{2(T-1)} \left\{ 1 - \frac{\tilde{u}' (\mathbf{I}_N \otimes \mathbf{J}_T) \tilde{u}}{\tilde{u}' \tilde{u}} \right\}^2,$$

$$LM_2 = \frac{NT}{2(N-1)} \left\{ 1 - \frac{\tilde{u}' (\mathbf{J}_N \otimes \mathbf{I}_T) \tilde{u}}{\tilde{u}' \tilde{u}} \right\}^2,$$

or one may test for one-way effects by using  $LM_1$  or  $LM_2$ . This test is due to BREUSCH & PAGAN.

## The Hausman test principle

*Hausman tests* can be used in all situations where two model specifications and two estimators are available with the following properties:

1. In the restricted model (null), the estimator  $\hat{\theta}$  is efficient, the estimator  $\tilde{\theta}$  is consistent though typically not efficient;
2. in the unrestricted model (alternative), the estimator  $\hat{\theta}$  is inconsistent, the estimator  $\tilde{\theta}$  is consistent.

Then, the difference  $q = \hat{\theta} - \tilde{\theta}$  should diverge under the alternative and it should converge to zero under the null. Moreover, under the null  $q$  and  $\hat{\theta}$  should be uncorrelated.

## The RE and the FE model

The null of the RE and the alternative of the FE model correspond to the Hausman situation:

1. In the RE model, the GLS-type RE estimator is efficient by construction for Gaussian errors, the FE estimator and even the OLS estimator are consistent;
2. in the FE model, the RE estimator is inconsistent, because of the omitted-variable effect, while FE is consistent by construction.

## Two views on the RE inconsistency in the FE model

1. The estimator  $(\mathbf{X}'\Omega^{-1}\mathbf{X})^{-1}\mathbf{X}'\Omega^{-1}y$  is inconsistent, if the true model is  $y = X\beta + Z_{\mu}\mu + \nu$ , as the regressors  $Z_{\mu}$  are omitted;
2. MUNDLAK showed that the RE estimator for a stochastic regression model with  $X$  and  $Z_{\mu}$  correlated is identical to the FE estimator: the RE estimator imposes independence of effects and covariates.

Some argue, however, that MUNDLAK's alternative is not really the same concept as the fixed-effects model.



## The Hausman test statistic

The Hausman test statistic is defined as

$$m = q'(\text{var}\hat{\beta}_{FE} - \text{var}\hat{\beta}_{RE})^{-1}q,$$

with  $q = \hat{\beta}_{FE} - \hat{\beta}_{RE}$ . Under RE, the matrix difference in brackets is positive, as the RE estimator is efficient and any other estimator has a larger variance.

The statistic  $m$  is distributed  $\chi^2$  under the null of RE, with degrees of freedom determined by the dimension of  $\beta$ ,  $K$ .

## $R^2$ in a panel model

Should the variation due to effects be part of the explained variation or not? If yes, the  $R^2$  has little to say on the importance of the substantial covariates  $\beta$ .

There is no unanimous agreement on which  $R^2$  to report in a panel. Some programs (STATA etc.) follow the suggestion by WOOLDRIDGE and report three measures: within  $R^2$ , between  $R^2$ , and overall  $R^2$ .

## The within $R^2$

For the *within*  $R^2$ , the *total sum of squares* TSS is defined as

$$TSS = \sum_{i=1}^N \sum_{t=1}^T (y_{it} - \bar{y}_i)^2,$$

i.e. after adjusting for effects. Then, also residuals in the *residual sum of squares* ESS rely on the 'purged' model, and the statistic

$$1 - \frac{ESS}{TSS}$$

is maximized by LSDV or the FE estimator.

## The between $R^2$

For the *between*  $R^2$ , the *total sum of squares* TSS is defined as

$$TSS = \sum_{i=1}^N (\bar{y}_i - \bar{y})^2,$$

i.e. just  $N$  individual time averages. Residuals in the *residual sum of squares* ESS also rely on the between model with  $N$  observations, and the statistic

$$1 - \frac{ESS}{TSS}$$

is maximized by the between estimator.

## The overall $R^2$

Finally, the *overall*  $R^2$  relies on the usual TSS definition

$$TSS = \sum_{t=1}^T \sum_{i=1}^N (y_{it} - \bar{y})^2,$$

and on residuals calculated without accounting for effects. It is maximized by pooled OLS.

Values for the three  $R^2$  may be compared. For example, if within and overall  $R^2$  are close, this is evidence for individual effects being not so important etc.