

# Protecting the environment: On the interplay between voluntary contributions and public policy

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# Motivation

- Recent OECD household survey reveals:
  - 11% regularly use a hybrid electric car
  - 18% have installed solar panels for electricity
  - 23% save energy for environmental reasons
- Yet, the dominant role in environmental protection is still played by governments
- Some policies receive public support, while others do not



## Research Question

**How does individual pro-environmental behavior affect public support for environmental policy and environmental quality in the long run?**

*Answer helps determine if advocating for personal actions to fight climate change is worthwhile*

# Our Approach

- A stylized model that incorporates individuals' contributions to env. protection and their support for env. policy
- Environmental quality is a public good
- Its provision is affected over time by:
  - economic development
  - voluntary contributions
  - environmental policy
- Voluntary contributions are motivated by 'warm glow'
- Policy decision is made on behalf of individuals alive

# Related Literature

- Private provision of an environmental public good
  - Jouvét et al. (2000), Nyborg et al. (2006), Kotchen & Moore (2007), Dam & Heijdra (2011), Bezin (2015), Perino (2015), Daube & Ulph (2016), Wichman (2016), Ambec & De Donder (2022), Aghion et al. (2023)
- Political economy of environmental policy
  - Bovenberg & Heijdra (1998, 2002), McAusland (2003), Cremer et al. (2004, 2008), Ono (2005), Balestra & Dottori (2012), Habla & Roeder (2013), Karp & Rezai (2014), Besley & Persson (2019)

# Overview of the Main Results

1. A stronger motivation for voluntary contributions leads to lower pollution taxes and a lower government pollution abatement in the long run
2. Without voluntary contributions, environmental quality is higher in the long run

# Model Setup: Environmental Quality

- Discrete time,  $t \in \{0, 1, \dots\}$
- Environment deteriorates as a by-product of production
- Environmental quality evolves according to

$$E_{t+1} = \Phi(E_t) - \gamma_y Y_t + \gamma_m m_t + \gamma_g g_t$$

- $Y_t$ : production level of the economy
- $m_t$ : abatement carried out by individuals
- $g_t$ : abatement carried out by the government
- It is realistic to assume  $\gamma_g > \gamma_m$

# Production

- Neoclassical production function,  $Y_t = F(K_t, L_t)$
- Capital depreciates fully in one period
- A representative firm chooses  $K_t$  and  $L_t$  to maximize

$$\pi_t = (1 - \tau_t \gamma_y) Y_t - R_t K_t - w_t L_t$$

- $\tau_t$ : pollution tax rate
- Perfectly competitive markets:

$$R_t = (1 - \tau_t \gamma_y) f'(k_t),$$

$$w_t = (1 - \tau_t \gamma_y) [f(k_t) - k_t f'(k_t)]$$



# Individuals

- A unit mass of identical individuals is born every  $t$
- Individuals live for one period
- Preferences of an individual born at  $t$  are represented by

$$U(c_t, x_t, m_t, E_{t+1})$$

- Environmental quality is a public good
  - ⇒ Each individual of generation  $t$  takes  $E_{t+1}$  as given
- The first- and second-period budget constraints are

$$c_t + x_t + (1 - \theta_t)m_t = w_t + R_t x_{t-1}$$

# Environmental Policy

- A balanced-budget environmental policy,

$$g_t + \theta_t m_t = \tau_t \gamma_y Y_t = \tau_t \gamma_y f(k_t)$$

- Denote by  $\sigma_t$  the share of tax revenues allocated to  $g_t$ , i.e.,

$$\sigma_t = \frac{g_t}{\tau_t \gamma_y f(k_t)}, \quad 1 - \sigma_t = \frac{\theta_t m_t}{\tau_t \gamma_y f(k_t)}$$

- Pair  $(\tau_t, \sigma_t)$  characterizes all feasible combinations of the environmental policy measures  $g_t$ ,  $\theta_t$  and  $\tau_t$

# Equilibrium for a Given Policy

## Definition 1

For a given sequence of environmental policy  $\{\tau_t, \sigma_t\}_{t=0}^{\infty}$  and a given initial state of the economy  $(k_0, E_0)$ , an equilibrium (path) is a sequence  $\{c_t, m_t, k_{t+1}, E_{t+1}\}_{t=0}^{\infty}$  such that for every period  $t \geq 0$ :

1. individuals solve their utility maximization problem,
2. firms solve their profit maximization problem,
3. all markets clear,
4. the law of motion for environmental quality is given by

$$E_{t+1} = \Phi(E_t) - (1 - \gamma_g \sigma_t \tau_t) \gamma_y f(k_t) + \gamma_m m_t.$$

# Short-Lived Government

- One-period lived government that chooses  $(\tau_t, \sigma_t)$
- It cares only about individuals alive in period  $t$
- Policy  $(\tau_t, \sigma_t)$  maximizes  $U(c_t, x_t, m_t, E_{t+1})$  subject to the equilibrium conditions
  - ⇒ Government internalizes the effect of  $m_t$  on  $E_{t+1}$
- Chosen  $(\tau_t, \sigma_t)$  depends on  $k_t$ , and  $E_t$

## Solving the Model

- We restrict attention to  $f(k) = k^\alpha$  and

$$U(c, x, m, E) = \ln c + \delta \ln x + \beta \ln m + \lambda \ln E$$

- The equilibrium (for a given policy) is characterized by

$$k_{t+1} = \frac{\delta(1 - \tau_t \gamma_y) k_t^\alpha}{1 + \delta + \beta} = \delta c_t,$$

$$E_{t+1} = \Phi(E_t) - (1 - \gamma_g \sigma_t \tau_t) \gamma_y k_t^\alpha + \gamma_m m_t,$$

with

$$m_t = \left[ \frac{\beta(1 - \tau_t \gamma_y)}{1 + \delta + \beta} + (1 - \sigma_t) \tau_t \gamma_y \right] k_t^\alpha$$

# Chosen Policy

Focus on an interior solution for  $(\tau_t, \sigma_t)$

## Proposition 1

*The interior solution for the time- $t$  government's problem is given by*

$$\tau_t = \frac{1}{\gamma_y} - \frac{(1 + \delta + \beta)[\Phi(E_t) + (\gamma_g - \gamma_y)k_t^\alpha]}{\gamma_y \gamma_g (1 + \delta + \beta + \lambda) k_t^\alpha},$$
$$\sigma_t = 1 - \frac{\beta \gamma_m (1 - \tau_t \gamma_y)}{\tau_t \gamma_y (\gamma_g - \gamma_m) (1 + \delta + \beta)}.$$

Both  $\tau_t$  and  $\sigma_t$  are high when environmental quality  $E_t$  is low and/or national income  $Y_t = k_t^\alpha$  is high

# Steady State

Suppose that  $\Phi(E_t)$  is linear:  $\Phi(E_t) = b\bar{E} + (1 - b)E_t$

## Proposition 2

*The capital stock  $k_t$  and the environmental quality  $E_t$  monotonically converge to their steady-state values  $k^* > 0$  and  $E^* > 0$ , respectively, if and only if  $\gamma_g \geq \gamma_y$  holds. These steady-state values are determined by*

$$k^* = \frac{\delta[b\bar{E} + (\gamma_g - \gamma_y)(k^*)^\alpha]}{\gamma_g(1 + \delta + \beta + \lambda b)},$$

$$E^* = \frac{\lambda[b\bar{E} + (\gamma_g - \gamma_y)(k^*)^\alpha]}{1 + \delta + \beta + \lambda b}.$$

## Long-Run Effects of Voluntary Contributions ( $\beta$ )

- Contributions divert resources from capital formation
  - ⇒ Direct negative effect on  $k^*$
- Contributions reduce the pollution tax
  - ⇒ Indirect positive effect on  $k^*$
- The first effect dominates, so that  $\partial k^*/\partial \beta < 0$



## Long-Run Effects of Voluntary Contributions (cont'd)

- Contributions improve environmental quality
  - ⇒ Direct positive effect on  $E^*$
- Contributions reduce pollution in the long run
  - ⇒ Indirect positive effect on  $E^*$
- Contributions reduce government abatement in the long run
  - ⇒ Indirect negative effect on  $E^*$
- The last effect dominates, so that  $\partial E^*/\partial \beta < 0$

# Conclusion

- Interplay between voluntary contributions and environmental policy
- A simple dynamic general-equilibrium model
- Environmental policy reflects public support
- Voluntary contributions reduce government abatement expenditures
  - ⇒ This reduces environmental quality in the long run
- Future work can deal with:
  - Two-sector economy, long-lived government, etc.