

Unbalanced Panel Data Models

Chapter 9 from Baltagi: Econometric Analysis of Panel
Data (2005)

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Introduction

- ‘balanced’ or ‘complete’ panels:
 - a panel data set where data/observations are available for all cross-sectional units in the entire sample period
- ‘unbalanced’ or ‘incomplete’ panels:
 - a panel data set where some data/observations are missing for some cross-sectional units in the sample period
- Randomly missing observations

Complete panel

person	year	income	age	sex
1	2003	1500	27	1
1	2004	1700	28	1
1	2005	2000	29	1
2	2003	2100	35	2
2	2004	2200	36	2
2	2005	2000	37	2

Incomplete panel

person	year	income	age	sex
1	2003	1500	27	1
1	2004	1700	28	1
2	2003	2000	31	2
2	2004	2100	32	2
2	2005	2200	33	2
3	2004	2000	30	1

The unbalanced one-way error component model

- The model: $y_{it} = \alpha + X'_{it}\beta + u_{it}$ where $\mu_i \sim IIN(0, \sigma_\mu^2)$
 $u_{it} = \mu_i + v_{it}$ $v_{it} \sim IIN(0, \sigma_v^2)$
 $i = 1, \dots, N$
 $t = 1, \dots, T_i$
- Vector form: $\underset{n \times 1}{y} = \alpha \underset{n \times 1}{1_n} + X \underset{n \times K}{\beta} + u$ where $Z = (1_n, X)$
 $\delta' = (\alpha', \beta')$
 $u = Z_\mu \mu + v$ $n = \sum T_i$
 $Z_\mu = \text{diag}(1_{T_i})$
- The OLS on the unbalanced data is given by: $\hat{\delta}_{OLS} = (Z'Z)^{-1} Z'y$

 - This is BLUE when $\sigma_\mu^2 = 0$.
 - If $\sigma_\mu^2 > 0$ then OLS is still unbiased and consistent, but its standard errors are biased.

Complete panel case

$$Z_{\mu} = I_N \otimes \iota_T = \begin{pmatrix} \begin{matrix} 1 \\ MT \\ 1 \\ 0 \\ MT \\ 0 \end{matrix} & \begin{matrix} 0 \\ MT \\ 0 \\ 1 \\ MT \\ 1 \end{matrix} & \begin{matrix} \Lambda \\ \\ \\ \\ \\ \end{matrix} & \begin{matrix} 0 \\ \\ \\ \\ \\ \end{matrix} \\ \\ \\ \\ \\ \begin{matrix} M \\ \\ \\ \\ \\ \end{matrix} & \begin{matrix} \\ \\ \\ \\ \\ \end{matrix} & \begin{matrix} \\ \\ \\ \\ \\ \end{matrix} & \begin{matrix} \\ \\ \\ \\ \\ \end{matrix} \\ \\ \\ \\ \begin{matrix} 0 \\ \Lambda \\ \\ \\ \end{matrix} & \begin{matrix} \\ \\ \\ \\ \end{matrix} & \begin{matrix} \begin{matrix} 0 \\ MT \\ 0 \end{matrix} & \begin{matrix} 1 \\ MT \\ 1 \end{matrix} \end{matrix} \end{pmatrix}$$

$$Z = (\iota_{NT}, \begin{matrix} \begin{matrix} \begin{matrix} 1 \\ MT \\ 1 \\ 1 \\ MT \\ 1 \end{matrix} \\ \begin{matrix} X_1 \\ X_2 \\ \\ X_N \end{matrix} \\ \begin{matrix} Tx(K-1) \\ Tx(K-1) \\ \\ Tx(K-1) \end{matrix} \end{matrix} \\ \begin{matrix} M \\ M \\ \\ M \end{matrix} \end{matrix}) = \begin{matrix} \begin{matrix} \begin{matrix} 1 \\ MT \\ 1 \\ 1 \\ MT \\ 1 \end{matrix} \\ \begin{matrix} X_1 \\ X_2 \\ \\ X_N \end{matrix} \\ \begin{matrix} Tx(K-1) \\ Tx(K-1) \\ \\ Tx(K-1) \end{matrix} \end{matrix} \\ \begin{matrix} M \\ M \\ \\ M \end{matrix} \end{matrix}$$

$NT \times K$

Incomplete panel case

$$Z_{\mu} = I_N \otimes \iota_{T_i} = \begin{pmatrix} \begin{matrix} 1 \\ MT_1 \\ 1 \\ 0 \\ MT_2 \\ 0 \end{matrix} & \begin{matrix} 0 \\ MT_1 \\ 0 \\ 1 \\ MT_2 \\ 1 \end{matrix} & \begin{matrix} \Lambda \\ \\ \\ \\ \\ \end{matrix} & \begin{matrix} 0 \\ \\ \\ \\ \\ \end{matrix} \\ \\ \\ \\ \\ \begin{matrix} M \\ \\ \\ \\ \\ \end{matrix} & \begin{matrix} \\ \\ \\ \\ \\ \end{matrix} & \begin{matrix} \\ \\ \\ \\ \\ \end{matrix} & \begin{matrix} \\ \\ \\ \\ \\ \end{matrix} \\ \\ \\ \\ \begin{matrix} 0 \\ \Lambda \\ \\ \\ \end{matrix} & \begin{matrix} \\ \\ \\ \\ \end{matrix} & \begin{matrix} \begin{matrix} 0 \\ MT_N \\ 0 \end{matrix} & \begin{matrix} 1 \\ MT_N \\ 1 \end{matrix} \end{matrix} \end{pmatrix}$$

$$Z = (\iota_n, \begin{matrix} \begin{matrix} \begin{matrix} 1 \\ MT_1 \\ 1 \\ 1 \\ MT_2 \\ 1 \end{matrix} \\ \begin{matrix} X_1 \\ X_2 \\ \\ X_N \end{matrix} \\ \begin{matrix} T_1x(K-1) \\ T_2x(K-1) \\ \\ T_Nx(K-1) \end{matrix} \end{matrix} \\ \begin{matrix} M \\ M \\ \\ M \end{matrix} \end{matrix}) = \begin{matrix} \begin{matrix} \begin{matrix} 1 \\ MT_1 \\ 1 \\ 1 \\ MT_2 \\ 1 \end{matrix} \\ \begin{matrix} X_1 \\ X_2 \\ \\ X_N \end{matrix} \\ \begin{matrix} T_1x(K-1) \\ T_2x(K-1) \\ \\ T_Nx(K-1) \end{matrix} \end{matrix} \\ \begin{matrix} M \\ M \\ \\ M \end{matrix} \end{matrix}$$

nxK

- $$\bar{J}_{T_i} = \frac{J_{T_i}}{T_i}$$

$$J_{T_i} = \begin{pmatrix} 64 & T_1 & 18 \\ 1 & \Lambda & 1 \\ M & & M & & 1 \\ 1 & \Lambda & 1 & & \\ & & 1 & \Lambda & 1 \\ & & M & & M & T_2 \times T_2 \\ & & 1 & \Lambda & 1 \\ & & & & & O \\ & & & & & & 1 & \Lambda & 1 \\ & 1 & & & & & M & & M \\ & & & & & & 1 & \Lambda & 1 \\ & & & & & & & & T_N \times T_N \end{pmatrix}$$

[illegible]

Incomplete panel \rightarrow

$$Q = \text{diag}(E_{T_i}) = \left(\begin{array}{cccc} \left. \begin{array}{cccc} 1 - \frac{1}{T_1} & -\frac{1}{T_1} & \Lambda & -\frac{1}{T_1} \\ -\frac{1}{T_1} & 1 - \frac{1}{T_1} & & M \\ M & & O & \\ -\frac{1}{T_1} & \Lambda & & 1 - \frac{1}{T_1} \end{array} \right\} T_1 \times T_1 & & & 0 \\ & \left. \begin{array}{ccc} 1 - \frac{1}{T_2} & & -\frac{1}{T_2} \\ & 1 - \frac{1}{T_2} & \\ & & O \end{array} \right\} T_2 \times T_2 & & \\ & & \left. \begin{array}{cc} -\frac{1}{T_2} & 1 - \frac{1}{T_2} \end{array} \right\} & & \\ & & & O & \\ & & & & \left. \begin{array}{ccc} 1 - \frac{1}{T_N} & & -\frac{1}{T_N} \\ & 1 - \frac{1}{T_N} & \\ & & O \end{array} \right\} T_N \times T_N \\ & & & & & \left. \begin{array}{cc} -\frac{1}{T_N} & 1 - \frac{1}{T_N} \end{array} \right\} \end{array} \right)$$

$$Q = I_{NT} - T^{-1} I_N \otimes J_T = \left(\begin{array}{cccc} \left. \begin{array}{cccc} 1 - \frac{1}{T} & -\frac{1}{T} & \Lambda & -\frac{1}{T} \\ -\frac{1}{T} & 1 - \frac{1}{T} & & M \\ M & & O & \\ -\frac{1}{T} & \Lambda & & 1 - \frac{1}{T} \end{array} \right\} T \times T & & & 0 \\ & \left. \begin{array}{ccc} 1 - \frac{1}{T} & & -\frac{1}{T} \\ & 1 - \frac{1}{T} & \\ & & O \end{array} \right\} T \times T & & \\ & & \left. \begin{array}{cc} -\frac{1}{T} & 1 - \frac{1}{T} \end{array} \right\} & & \\ & & & O & \\ & & & & \left. \begin{array}{ccc} 1 - \frac{1}{T} & & -\frac{1}{T} \\ & 1 - \frac{1}{T} & \\ & & O \end{array} \right\} T \times T \\ & & & & & \left. \begin{array}{cc} -\frac{1}{T} & 1 - \frac{1}{T} \end{array} \right\} \end{array} \right)$$

\leftarrow Complete panel

- Within residuals \tilde{u} for the unbalanced panels are given by:

$$\tilde{u} = y - \tilde{\alpha} \iota_N - X\tilde{\beta}$$

$$\tilde{\alpha} = (\bar{y}_{..} - \bar{X}_{..}\tilde{\beta})$$

$$\bar{y}_{..} = \frac{\sum \sum y_{it}}{n}$$

- The Between estimator and the Between residuals are obtained as follows:

$$\hat{\delta}_{Between} = (Z' P Z)^{-1} Z' P y$$

$$P = \text{diag}[\bar{J}_{T_i}]$$

$$\hat{u}^b = y - Z\hat{\delta}_{Between}$$

The unbalanced two-way error component model

- The fixed effects model:

- Wansbeek and Kapteyn (1989) consider the following model:

$$y_{it} = \alpha + X'_{it}\beta + u_{it}$$

$$u_{it} = \mu_i + \lambda_t + v_{it}$$

$$i = 1, \dots, N_t$$

$$t = 1, \dots, T$$

- Furthermore define the matrix Δ that gives the dummy-variable structure for the incomplete data model:

$$\Delta = (\Delta_1, \Delta_2) \equiv \begin{bmatrix} D_1 & D_1 \iota_N & & \\ M & & O & \\ D_T & & & D_T \iota_N \end{bmatrix}$$

$$\Delta_1 = (D_1', D_2', D_3')'_{nxN}$$

$$\Delta_2 = \text{diag}[D_t \iota_N]_{nxT} = \text{diag}[\iota_N]_{nxT}$$

- D_t is $N_t \times N$ matrix obtained from I_N by omitting the rows corresponding to individuals not observed in year t

- For complete panels:

$$\Delta_1 = (\iota_T \otimes I_N)$$

$$\Delta_2 = I_T \otimes \iota_N$$

- If μ_i and λ_t are fixed, one has to run the regression with the matrix of dummies on the previous slide
- However, it is infeasible for large panels \rightarrow Within transformation needed

• Incomplete case:



• Complete case:

$$P_{[\Delta]} = P_{\Delta_1} + P_{[Q_{[\Delta_1]} \Delta_2]} \quad \text{and}$$

$$Q_{[\Delta]} = Q_{[\Delta_1]} - Q_{[\Delta_1]} \Delta_2 (\Delta_2' Q_{[\Delta_1]} \Delta_2)^{-1} \Delta_2' Q_{[\Delta_1]}$$

$$Q_{[\Delta]} = I_n - P_{[\Delta]} \quad \text{where} \quad P_{[\Delta]} = \Delta(\Delta' \Delta)^{-1} \Delta'$$

and

$$\Delta_N \equiv \Delta_1' \Delta_1 = \text{diag}[T_i]$$

$$\Delta_T \equiv \Delta_2' \Delta_2 = \text{diag}[N_t]$$

$$\Delta_{TN} \equiv \Delta_2' \Delta_1$$



$$\Delta_N = T I_N$$

$$\Delta_T = N I_T$$

$$\Delta_{TN} = \iota_T \iota_N' = J_{TN}$$

- Extensions to higher-order error component model (e.g. 3-way):
(Davis (2001))

$$\Delta = [\Delta_1, \Delta_2, \Delta_3]$$

$$Q_{[\Delta]} = Q_{[A]} - P_{[B]} - P_{[C]}$$

$$A = \Delta_1$$

$$B = Q_{[A]} \Delta_2$$

$$C = Q_{[B]} Q_{[A]} \Delta_3$$

- The random effects model:

- Vector form of the model: $u = \Delta_1 \underbrace{\mu}_{N \times 1} + \Delta_2 \underbrace{\lambda}_{T \times 1} + \underbrace{\nu}_{n \times 1}$ where $\mu \sim (0, \sigma_\mu^2)$
 $\lambda \sim (0, \sigma_\lambda^2)$
 $\nu \sim (0, \sigma_\nu^2)$

- Variance matrix: $\Omega = E(uu') = \sigma_\nu^2 I_n + \sigma_\mu^2 \Delta_1 \Delta_1' + \sigma_\lambda^2 \Delta_2 \Delta_2' =$
 $= \sigma_\nu^2 (I_n + \phi_1 \Delta_1 \Delta_1' + \phi_2 \Delta_2 \Delta_2') = \sigma_\nu^2 \Sigma$

where $\phi_1 = \sigma_\mu^2 / \sigma_\nu^2$

$\phi_2 = \sigma_\lambda^2 / \sigma_\nu^2$

- Using the general expression for the inverse of $(I + X'X)$, one obtains

$$\Sigma^{-1} = V - V \Delta_2 \tilde{P}^{-1} \Delta_2' V \quad \text{where}$$

$$V = I_n - \Delta_1 \tilde{\Delta}_N^{-1} \Delta_1'$$

$$\tilde{P} = \tilde{\Delta}_T - \Delta_{TN} \tilde{\Delta}_N^{-1} \Delta_{TN}'$$

$$\tilde{\Delta}_N = \Delta_N + (\sigma_\nu^2 / \sigma_\mu^2) I_N$$

$$\tilde{\Delta}_T = \Delta_T + (\sigma_\nu^2 / \sigma_\lambda^2) I_T$$

- Davis (2001) shows that this result can be generalized to an arbitrary number of random error components, e.g. 3-way model:

$$\Omega = E(uu') = \sigma_\nu^2 I_n + \sigma_\mu^2 \Delta_1 \Delta_1' + \sigma_\lambda^2 \Delta_2 \Delta_2' + \sigma_\eta^2 \Delta_3 \Delta_3'$$

- Wansbeek and Kapteyn suggest an ANOVA-type quadratic unbiased estimator of the variance components based on the Within residuals

$$q_W = e' Q_{[\Delta]} e$$

- Let $e = y - X\tilde{\beta}$ and define $q_N = e' \Delta_2 \Delta_T^{-1} \Delta_2' e = e' P_{[\Delta_2]} e$

$$q_T = e' \Delta_1 \Delta_N^{-1} \Delta_1' e = e' P_{[\Delta_1]} e$$

- By equating q_W, q_N, q_T to their expected values and solving these three equations one gets QUE of $\sigma_v^2, \sigma_\mu^2, \sigma_\lambda^2$

Testing for individual and time effects using unbalanced panel data

- Baltagi and Li (1990) derived a corresponding LM test for the unbalanced two-way error component model
- Under normality of disturbances the LM statistic is given by

$$LM = \left(\frac{1}{2}\right)n^2 [A_1^2 / (M_{11} - n) + A_2^2 / (M_{22} - n)]$$

$$A_r = [(\tilde{u}' \Delta_r \Delta_r' \tilde{u} / \tilde{u}' \tilde{u}) - 1]$$

$$M_{11} = \sum_{i=1}^N T_i^2$$

$$M_{22} = \sum_{t=1}^T N_t^2$$

which is asymptotically distributed as χ_2^2 under the null hypothesis

($H_0 : \sigma_\mu^2 = \sigma_\lambda^2 = 0$)

- If $H_0 : \sigma_\mu^2 = 0$ then $LM = \left(\frac{1}{2}\right)n^2 [A_1^2 / (M_{11} - n)]$ and it is asymptotically distributed as χ_1^2
- If $H_0 : \sigma_\lambda^2 = 0$ then $LM = \left(\frac{1}{2}\right)n^2 [A_2^2 / (M_{22} - n)]$ and it is asymptotically distributed as χ_1^2

- These variance components cannot be negative and therefore the alternative hypotheses are (Moulton and Randolph (1989)):
 $H_A : \sigma_\mu^2 > 0$ and $H_A : \sigma_\lambda^2 > 0$ and the one-sided LM statistics are given by:

$$SLM = \frac{LM_1 - E(LM_1)}{\sqrt{\text{var}(LM_1)}} = \frac{d - E(d)}{\sqrt{\text{var}(d)}} \quad \text{and} \quad LM_2 = n[2((M_{22} - n))]^{-1/2} A_2$$

$$LM_1 = n[2(M_{11} - n)]^{-1/2} A_1$$

$$d = (\tilde{u}' D \tilde{u}) / \tilde{u}' \tilde{u}$$

$$D = \Delta_1 \Delta_1'$$

- Under the null hypothesis they have asymptotic $N(0,1)$ distribution
- Honda's (1985) one-sided for the two-way model with unbalanced data is simply: $HO = (LM_1 + LM_2) / \sqrt{2}$
- Baltagi, Chang and Li (1998): the locally mean most powerful one-sided test for unbalanced two-way error component model is given by (King and Wu (1997)):

$$KM = \frac{\sqrt{M_{11} - n}}{\sqrt{M_{11} + M_{22} - 2n}} LM_1 + \frac{\sqrt{M_{22} - n}}{\sqrt{M_{11} + M_{22} - 2n}} LM_2$$

- Both tests are asymptotically distributed as $N(0,1)$ under H_0

- These tests can be standardized and the resulting SLM given by:
 - For Honda's version:
$$D = \frac{1}{2} \frac{n}{\sqrt{M_{11} - n}} (\Delta_1 \Delta'_1) + \frac{1}{2} \frac{n}{\sqrt{M_{22} - n}} (\Delta_2 \Delta'_2)$$
 - For the King and Wu version:
$$D = \frac{n}{\sqrt{2} \sqrt{M_{11} + M_{22} - 2n}} [(\Delta_1 \Delta'_1) + (\Delta_2 \Delta'_2)]$$
- Since LM1 and LM2 can be negative for a specific application, especially when one or both variance components are small or close to zero → GHM test (Gourieroux, Holly and Monfort (1982)):

$$\chi_m^2 = \begin{cases} LM_1^2 + LM_2^2 & \text{if } LM1 > 0, LM2 > 0 \\ LM_1^2 & \text{if } LM1 > 0, LM2 \leq 0 \\ LM_2^2 & \text{if } LM1 \leq 0, LM2 > 0 \\ 0 & \text{if } LM1 \leq 0, LM2 \leq 0 \end{cases} \quad \text{and } \chi_m^2 \sim \left(\frac{1}{4}\right) \chi^2(0) + \left(\frac{1}{2}\right) \chi^2(1) + \left(\frac{1}{4}\right) \chi^2(2)$$

- Recommendation:
 - The use of standardized version of these tests

Thank you for your attention!