

Nonparametric Density Estimation

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Introduction

- Nonparametric function estimation: Smoothing and density estimation
- Smoothing techniques: Useful graphic tool for summarizing the marginal distribution of a given time series
- Time domain smoothing and State domain smoothing (actual vs. lagged series)
- Smoothing used to estimate spectral density to examine cyclic patterns, white noise of residuals (of a fitted model),...
- Density estimation is the simplest nonparametric function estimation

Kernel density estimation (1)

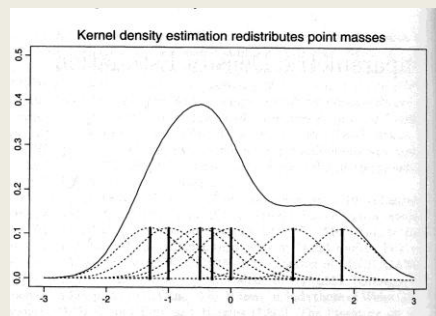
- Used to examine the overall distribution of a data set
- Improvement to histogram method
- Number and locations of peaks/throughs and symmetry of a density
- Empirical distribution function:

$$\hat{F}(x) = \frac{1}{T} \sum_{i=1}^T I(X_i \leq x)$$

- T data points X_1, \dots, X_T
- Putting mass $1/T$ at each observed datum

Kernel density estimation (2)

- Problem: Nondecreasing function, not very useful in examining the overall structure
- Density function would be better, but density of an empirical function does not exist
- Solution: take mass $1/T$ at each datum point, redistribute it, add up

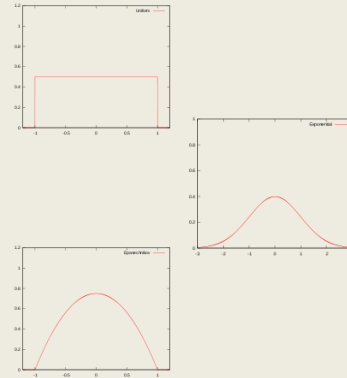


Different kernel functions (1)

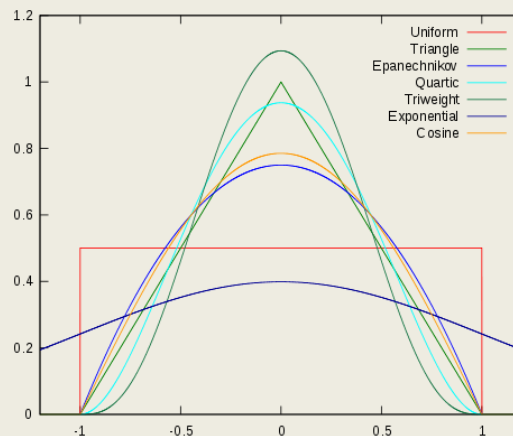
- Kernel density estimate

$$\hat{f}_h(x) = \frac{1}{T} \sum_{t=1}^T K_h(X_t - x) = \int K_h(X_t - x) d\hat{F}(u) \quad K_h(\cdot) = K(\cdot/h)/h$$

- Uniform $K(u) = \frac{1}{2} \mathbf{1}_{\{|u| \leq 1\}}$
- Gaussian $K(u) = (\sqrt{2\pi})^{-1} e^{-u^2/2}$
- Epanechnikov $K(u) = \frac{3}{4} (1-u^2) \mathbf{1}_{\{|u| \leq 1\}}$
- Biweight $K(u) = \frac{15}{16} (1-u^2)^2 \mathbf{1}_{\{|u| \leq 1\}}$
- Triweight $K(u) = \frac{35}{32} (1-u^2)^3 \mathbf{1}_{\{|u| \leq 1\}}$



Different kernel functions (2)



How to do it?

- Practically: Choose Kernel function and bandwidth h
- „It is well-known both empirically and theoretically that the choice of kernel functions is not very important to the kernel density estimator.“
- ... if the kernel is symmetric and unimodal, and if bandwidth h is optimally chosen

Optimal bandwidth h (1)

- Mean square error (pointwise):

$$MSE(x) \equiv E \{ \hat{f}_h(x) - f(x) \}^2$$

- Mean integrated squared error (global):

$$MISE \equiv E \int_{-\infty}^{\infty} \{ \hat{f}_h(x) - f(x) \}^2 dx$$

- Minimize MISE w.r.t. h :

$$h_{opt} = \alpha(K) \|f''\|_2^{-2/5} T^{-1/5}$$

$$\alpha(K) = \mu_2(K)^{-2/5} \|K\|_2^{2/5}$$

$$\mu_2(K) = \int_{-\infty}^{+\infty} u^2 K(u) du \quad \text{is the variance of } K$$

$$\|g\|_2^2 = \int_{-\infty}^{+\infty} g(u)^2 du \quad \text{is the } L_2\text{-norm}$$

Optimal bandwidth h (2)

- Optimal MISE (with optimal bandwidth):

$$\frac{5}{4}\beta(K)\|f''(x)\|_2^{2/5}T^{-4/5} \quad \beta(K) = \mu_2(K)^{2/5}\|K\|_2^{8/5}$$

TABLE 5.1. Some useful constants related to the kernel functions.

Functional	Gaussian	Uniform	Epanechnikov	Biweight	Triweight
$\mu_2(K)$	1	0.3333	0.2000	0.1429	0.1111
$\ K\ _2^2$	0.2821	0.5000	0.0600	0.7143	0.8159
$\alpha(K)$	0.7764	1.3501	1.7188	2.0362	2.3122
$\beta(K)$	0.3633	0.3701	0.3491	0.3508	0.3529

- Note: β nearly the same

- $$h_1 = \frac{\alpha(K_1)}{\alpha(K_2)}h_2$$

Optimal bandwidth h (3)

- Practically, most parameters cannot be observed

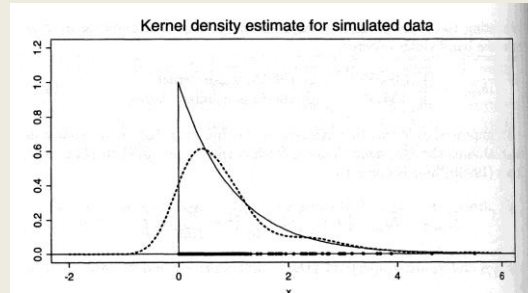
$$h_{opt,T} = (8\sqrt{\pi}/3)^{1/5} \alpha(K) \sigma T^{-1/5}$$

- Replace unknown parameters by observed (sample) measures, solve constants numerically

- $$\hat{h}_{opt,n} = \begin{cases} 1.06sT^{-1/5} & \text{for Gaussian kernel} \\ 2.34sT^{-1/5} & \text{for Epanechnikov kernel} \end{cases}$$

- Good if data is Gaussian, oversmooths if data is asymmetric or multimodal

Boundary Correction



- Reflection:
$$\hat{f}_h^*(x) = \frac{1}{T} \left\{ \sum_{i=1}^T K_h(X_i - x) + \sum_{i=1}^T K_h(-X_i - x) \right\} \quad x \geq 0$$
- Transformation:
$$\hat{f}_x(x) = g'(x) T^{-1} \sum_{i=1}^T K_h(g(x) - g(X_i))$$